# EXISTENCE THEOREMS FOR NONLINEAR DIFFERENTIAL EQUATIONS HAVING TRICHOTOMY IN BANACH SPACES 

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Abstract. We give existence theorems for weak and strong solutions with trichotomy of the nonlinear differential equation

$$
\begin{equation*}
\dot{x}(t)=\mathcal{L}(t) x(t)+f(t, x(t)), \quad t \in \mathbb{R} \tag{P}
\end{equation*}
$$

where $\{\mathcal{L}(t): t \in \mathbb{R}\}$ is a family of linear operators from a Banach space $E$ into itself and $f: \mathbb{R} \times E \rightarrow E$. By $L(E)$ we denote the space of linear operators from $E$ into itself. Furthermore, for $a<b$ and $d>0$, we let $C([-d, 0], E)$ be the Banach space of continuous functions from $[-d, 0]$ into $E$ and $f^{d}:[a, b] \times C([-d, 0], E) \rightarrow E$. Let $\widehat{\mathcal{L}}:[a, b] \rightarrow L(E)$ be a strongly measurable and Bochner integrable operator on $[a, b]$ and for $t \in[a, b]$ define $\tau_{t} x(s)=x(t+s)$ for each $s \in[-d, 0]$. We prove that, under certain conditions, the differential equation with delay

$$
\begin{equation*}
\dot{x}(t)=\widehat{\mathcal{L}}(t) x(t)+f^{d}\left(t, \tau_{t} x\right) \quad \text { if } t \in[a, b], \tag{Q}
\end{equation*}
$$

has at least one weak solution and, under suitable assumptions, the differential equation $(Q)$ has a solution. Next, under a generalization of the compactness assumptions, we show that the problem $(\mathrm{Q})$ has a solution too.

Keywords: nonlinear differential equation; trichotomy; existence theorem
MSC 2010: 35F31, 34D09

## 1. Introduction

In Section 2, we investigate the weak and strong solutions of the problem having trichotomy

$$
\begin{equation*}
\dot{x}(t)=\mathcal{L}(t) x(t)+f(t, x(t)), \quad t \in \mathbb{R} . \tag{P}
\end{equation*}
$$

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Main results of this section generalize many previous theorems. In fact, in the case $\mathcal{L}(t)=0$ we have, as a special case, some improvement to the existence theorem of Cramer-Lakshmikantham-Mitchell in [9], Boudourides in [2], Ibrahim-Gomaa in [21], Szep in [36] and Papageorgiou in [30]. Cramer-Lakshmikantham-Mitchell in [9] studied the special case of Problem (P) in a nonreflexive Banach space, Boudourides in [2] and Papageorgiou in [30] found weak solutions for the special case of Problem (P) on a finite interval $[0, T]$ with $0<T<\infty$. Szep in [36] studied the special case of Problem ( P ) in a reflexive Banach space, while we use in this section more general compactness assumptions. Ibrahim-Gomaa [21] proved the existence of weak solutions for the special case of Problem (P) on a finite interval [0,T]. Also in [14] we consider the Cauchy problem by using weak and strong measures of noncompactness while in [17] we consider some differential inclusions and its topological properties with delay. In [35] the authors present necessary and sufficient conditions for uniform exponential trichotomy of evolution families on the real line, but in [27] Megan-Stoica deal with necessary and sufficient conditions for uniform exponential trichotomy of nonlinear evolution operators in Banach spaces. Moreover, the nonlinear differential equations were studied by many authors ([6], [7], [15], [19], [22], [25], [26] for instance). Further, the paper [3] contains also a suggestion how to apply the results presented in that paper.

In fact, if $\mathcal{L}(t) \neq 0$ our main results generalize those of Cichoń in [4], [6] because we are able to reduce the compactness assumptions.

Finally, in Section 4 we examine the equation

$$
\begin{equation*}
\dot{x}(t)=\widehat{\mathcal{L}}(t) x(t)+f^{d}\left(t, \tau_{t} x\right) \quad \text { if } t \in[a, b], \tag{Q}
\end{equation*}
$$

and obtain results similar to that for problem (P). Recently the difference equations (even in the context of Banach spaces) have been investigated (cf. [31], [34]).

## 2. Preliminaries

Let $E$ be a Banach space, $E^{*}$ its dual space and $E_{w}$ the Banach space $E$ endowed with the weak topology. Let $\lambda$ be the Lebesgue measure on $\mathbb{R}^{+}, B_{E}$ the family of all nonempty bounded subsets of $E$ and $R_{E}$ the family of all nonempty and relatively weakly compact subsets of $E$. Assume that $\langle$,$\rangle is the pairing between E$ and $E^{*}$ and $C_{(w)}(\mathbb{R}, E)$ is the space of all (weakly) continuous functions from $\mathbb{R}^{+}$to $E$ endowed with the topology of almost uniform weak convergence. Further, let $C([-d, 0], E)$ be the Banach space of continuous functions from the closed interval $[-d, 0], d \geqslant 0$ into $E$. By $L(E)$ we will denote the space of linear operators from $E$ into itself. A function $u:[a, b] \rightarrow E,(a, b) \in \mathbb{R}^{2}$ is called Pettis integrable if for any measurable
subset $D$ of $[a, b]$ there is an element $v_{D}$ in $E$ such that $\left\langle v_{D}, f\right\rangle=\int_{D}\langle u(s), f\rangle \mathrm{d} s$ for all $f \in E^{*}$; in this case we write $v_{D}=\int_{D} u(s) \mathrm{d} s$. A function $u:[a, b] \rightarrow E$ is called Bochner integrable if there exists a sequence of countable-valued functions $\left\{u_{n}\right\}$ converging almost everywhere on $[a, b]$ such that $\lim _{n \rightarrow \infty} \int_{a}^{b}\left\|u_{n}(s)-u(s)\right\| \mathrm{d} s=0$. We note that every Bochner integrable function is Pettis integrable (see [20]).

For any nonempty bounded subset $Z$ of $E$ we recall the definition of De Blasi's measure of weak noncompactness:

$$
\beta(Z)=\inf \left\{\varepsilon>0: \exists K=\text { weakly compact subset of } E, Z \subseteq K+\varepsilon B_{1}\right\} .
$$

For the properties of $\beta$ see [1], [13].
If we put $\mathbb{R}^{a}=\{x: z \leqslant x<\infty, z=\min \{a, 0\}\}$, then by a Kamke function we mean a function $w:[a, b] \times \mathbb{R}^{a} \rightarrow \mathbb{R}^{+}$such that
(i) $w$ satisfies the Carathéodory conditions,
(ii) for all $t \in[a, b] ; w(t, a)=0$,
(iii) for any $c \in(a, b], u \equiv 0$ is the only absolutely continuous function on $[a, c]$ which satisfies $\dot{u}(t) \leqslant w(t, u(t))$ a.e. on $[a, c]$ and such that $u(a)=0$.

A nonempty family $K \subset R_{E}$ is a kernel if it satisfies the following conditions:
(i) $A \in K \Rightarrow \operatorname{conv} A \in K$,
(ii) $B \neq \emptyset, B \subset A, A \in K \Rightarrow B \in K$,
(iii) a subfamily of all weakly compact sets in $K$ is closed in the family of all bounded and closed subsets of $E$ with the topology generated by the Hausdorff distance.

A function $\gamma: B_{E} \rightarrow[0, \infty)$ is a measure of noncompactness with the kernel $K$ if it is subject to the following conditions:
(i) $\gamma(A)=0 \Rightarrow A \in K$,
(ii) $\gamma(A)=\gamma(\bar{A})$, where $\bar{A}$ is the weak closure of the set $A$,
(iii) $\gamma(\operatorname{conv} A)=\gamma(A)$,
(iv) $A, B \in B_{E}, B \subset A \Rightarrow \gamma(B) \leqslant \gamma(A)$, see [1], [23].

Denote by $N$ a basis of neighbourhoods of zero in a locally convex space composed of closed convex sets. Let $N^{\prime}=\{r V: V \in N, r>0\}$. The following two definitions can be found in [5], [6].

A function $p: N^{\prime} \rightarrow[0, \infty)$ is a $p$-function if it satisfies the following conditions:
(i) $X, Y \in N^{\prime}, X \subset Y \Rightarrow p(X) \leqslant p(Y)$,
(ii) for each $\varepsilon>0$ there exists $X \in N^{\prime}$ such that $p(X)<\varepsilon$, (iii) $p(X)>0$ whenever $X \notin K$.

A function $\gamma: B_{E} \rightarrow[0, \infty)$ is a $(K, N, p)$-measure of noncompactness if and only if

$$
\gamma(U)=\inf \left\{\varepsilon>0: \exists A \in K, X \in N^{\prime}, U \subset A+X, p(X) \leqslant \varepsilon\right\}
$$

for each $U \in B_{E}$.
Each ( $K, N, p$ )-measure of noncompactness is a measure of weak noncompactness. De Blasi's measure is ( $K, N, p$ )-measure of noncompactness [1], [5].

For each $t \in \mathbb{R}$ and $\mathcal{L}(t) \in L(E)$, we consider the differential equation

$$
\begin{equation*}
\dot{x}(t)=\mathcal{L}(t) x(t) \tag{1}
\end{equation*}
$$

Following Elaydi and Hájek in [11] we introduce:
Let $X(t)$ be the fundamental solution of the differential equation $\dot{X}(t)=\mathcal{L}(t) X(t)$ with the condition $X(0)=$ Id. A linear equation (1) is said to have a trichotomy on $\mathbb{R}$ if there exist linear projections $P, Q$ such that

$$
P Q=Q P, \quad P+Q=P Q
$$

and constants $\alpha \geqslant 1, \sigma>0$ with

$$
\begin{aligned}
\left|X(t) P X^{-1}(s)\right| \leqslant \alpha \mathrm{e}^{-\sigma(t-s)} & \text { if } 0 \leqslant s \leqslant t \\
\left|X(t)(\operatorname{Id}-P) X^{-1}(s)\right| \leqslant \alpha \mathrm{e}^{-\sigma(s-t)} & \text { if } t \leqslant s, s \geqslant 0 \\
\left|X(t) Q X^{-1}(s)\right| \leqslant \alpha \mathrm{e}^{-\sigma(s-t)} & \text { if } 0 \leqslant s \leqslant 0 \\
\left|X(t)(\operatorname{Id}-Q) X^{-1}(s)\right| \leqslant \alpha \mathrm{e}^{-\sigma(t-s)} & \text { if } s \leqslant t, s \leqslant 0
\end{aligned}
$$

Define the integral kernel $K(t, s)=X(t) L(t, s) X^{-1}(s)$, where

$$
L(t, s)= \begin{cases}\operatorname{Id}-Q & \text { if } 0 \leqslant s \leqslant \max (t, 0) \\ -Q & \text { if } \max (t, 0)<s \\ P & \text { if } s \leqslant \min (t, 0) \\ P-\mathrm{Id} & \text { if } \min (t, 0)<s \leqslant 0\end{cases}
$$

Moreover, in [24] the authors consider two trichotomy concepts in the sense of ElaydiHájek in the general case of abstract evolution operators. Now for each $t, s \in \mathbb{R}$ we have $|K(t, s)| \leqslant \alpha \mathrm{e}^{-\sigma(t-s)}$ ([11], Lemma 7).

We will need the following lemmas in the proof of the main results.

Lemma 2.1 ([5]). If $\gamma$ is an $\left(R_{E}, N, p\right)$-measure of noncompactness such that $p(\alpha X)=\alpha p(X)$ with $X \in N^{\prime}, \alpha \in \mathbb{R}^{+}$and for each $X, Y \in N^{\prime}$ we have $X+Y \in N^{\prime}$, then
$\left(\mathrm{M}_{1}\right) \gamma(U+V) \leqslant \gamma(U)+\gamma(V)$,
$\left(\mathrm{M}_{2}\right) \gamma(\alpha U)=\alpha \gamma(U)$,
$\left(\mathrm{M}_{3}\right) \gamma(U \cup\{x\})=\gamma(U), x \in E$,
$\left(\mathrm{M}_{4}\right) U \subseteq V \Rightarrow \gamma(U) \leqslant \gamma(V)$,
$\left(\mathrm{M}_{5}\right) \gamma(\overline{\mathrm{conv}} U)=\gamma(U)$,
$\left(\mathrm{M}_{6}\right) \gamma(U)=0 \Rightarrow U$ is relatively compact in $E$.
Under the assumptions in Lemma 2.1 on the measure $\gamma$ we state the following lemma.

Lemma 2.2 ([16]). Let $V \subseteq C(I, E)$ be bounded equicontinuous in the strong topology and $V(J)=\{x(t): x \in V, t \in J\}$, where $J$ is a subinterval of $I$. Then, under the assumptions in Lemma 2.1, $\gamma(V(J))=\sup _{t \in J} \gamma(V(\{t\}))=\gamma((J(s))$ for some $s \in J$.

Lemma 2.3 ([6]). Let $\gamma$ be an $\left(R_{E}, N, p\right)$-measure of noncompactness such that $p(\alpha X)=\alpha p(X)$ with $X \in N^{\prime}, \alpha \in \mathbb{R}$ and $N$ is composed of balanced sets. Then for each bounded subset $U$ of $E$ and for each $A \in L(E)$, we have $\gamma(A U) \leqslant|A| \gamma(U)$.

Lemma 2.4 ([11]). Let $\xi(t)$ be a nonnegative locally integrable function such that

$$
\int_{t}^{t+1} \xi(s) \mathrm{d} s \leqslant b, \quad t \in \mathbb{R}
$$

If $\alpha>0$, then for all $t \in \mathbb{R}$

$$
\int_{-\infty}^{\infty} \mathrm{e}^{-\alpha|t-s|} \xi(s) \mathrm{d} s \leqslant \frac{2 b}{1-\mathrm{e}^{-\alpha}}
$$

Lemma 2.5 ([4]). If $D:[a, b] \rightarrow L(E)$ is a continuous mapping and $U$ is a bounded subset of $E$, then

$$
\gamma\left(\bigcup_{t \in[a, b]} D(t) U\right) \leqslant \sup _{t \in[a, b]}|D(t)| \gamma(U)
$$

Lemma 2.6 ([10]). Let $W$ be a bounded, almost equicontinuous subset of $C(\mathbb{R}, E)$. For any subset $X$ of $W$ set $\aleph(X)=\sup _{t \in \mathbb{R}} \gamma(X(t))$. Then $\aleph$ has the properties $\left(\mathrm{M}_{1}\right)-\left(\mathrm{M}_{5}\right)$ in Lemma 2.1 and if $\aleph(x)=0$, then $x$ is relatively compact in $C(\mathbb{R}, E)$.

Lemma 2.7 ([8]). Let $Y$ and $E$ be two Banach spaces, $P_{f c}(Y)$ the set of all closed and convex subsets of $Y$ and let $F: E \rightarrow P_{f c}(Y)$ be weakly sequentially upper hemicontinuous. Further let $\left(x_{n}\right)_{n \in \mathbb{N}} \subset C(I, E), x_{n}(t) \rightarrow x_{0}(t)$ weakly a.e. on $I$ and $\left(y_{n}\right)_{n \in \mathbb{N} \cup\{0\}} \subset L^{1}(I, E), y_{n} \rightarrow y_{0}$ weakly. Suppose that there exists $a \in L^{1}(I, \mathbb{R})$ such that $\|F(x)\| \leqslant a(t)$ for all $x \in C(I, E)$ and $y_{n}(t) \in F\left(x_{n}(t)\right)$ a.e. on $I$. Then $y_{0}(t) \in F\left(x_{0}(t)\right)$ a.e. on $I$.

Lemma 2.8 ([28]). Let $V \subseteq C(I, E)$ be a family of strongly equicontinuous functions. Then

$$
\beta_{c}(V)=\sup _{t \in I} \beta(V(t)),
$$

where $\beta_{c}(V)$ is the measure of weak noncompactness in $C(I, E)$ and $t \mapsto \beta(V(t))$ is a continuous function.

We need to state the well-known Darbo-Sadovskii's theorem [33].
Theorem 2.9. Let $\mu$ be a measure of noncompactness defined on a normed space $M$ such that $\mu(\overline{\text { conv }} U)=\mu(U)$ for any nonempty and bounded subset $U$ of $M$. Let $D$ be a nonempty bounded closed and convex subset of $M$. If $T: D \rightarrow M$ is continuous and for each bounded $A \subseteq D$ with $\mu(A)>0, \mu(T(A))<\mu(A)$, then $T$ has a fixed point.

Now we consider the Cauchy problem

$$
\left\{\begin{array}{l}
\dot{x}(t)=h\left(t, \tau_{t} x\right)  \tag{C}\\
x(t)=\psi \in C([-d, 0], E)
\end{array}\right.
$$

where $h:[0, \infty) \times C([-d, 0], E) \rightarrow E, x \in C([-d, \infty), E)$ and $\tau_{t} x \in C([-d, 0], E)$, $t \geqslant 0$ is defined by $\tau_{t} x(s)=x(t+s), s \in[-d, 0]$. Let $B_{r}=\{x \in C([-d, 0), E)$ : $\|x\| \leqslant r\}$.

Theorem 2.10 ([3], Theorem 5). Suppose that $E$ is a separable Banach space. Let $h:[0, \infty) \times C([-d, 0], E) \rightarrow E$ be sequentially weakly continuous in bounded sets. Further, let $h\left([0, T] \times B_{r}\right)$ be relatively compact in $E_{w}$ for any $T, r>0$. Then for each $r>0$ there exists $\delta(r)>0$ such that if $\psi \in C([-d, 0], E)$ and $\|\psi\| \leqslant r$, problem (C) has a solution defined on $[0, \delta]$. Moreover, if $h$ is continuous, then problem (C) has a solution in $C^{1}([0, \delta] ; E)$ and the separability of $E$ is not needed.

## 3. Existence results for problem (P)

In the following we study the problem ( P ) on $\mathbb{R}$ and use the $(K, N, p)$-measure of noncompactness so that we will generalize Theorem 8 with respect to the Cauchy problem in [14] and the references herein.

Theorem 3.1. We introduce the following assumptions:
$\left(\mathrm{M}_{1}\right) f$ is a continuous function from $\mathbb{R} \times E_{w}$ to $E_{w}$.
$\left(\mathrm{M}_{2}\right) \mathcal{L}: \mathbb{R} \rightarrow L(E)$ is strongly measurable and Bochner integrable on every finite subinterval of $\mathbb{R}$ and the linear equation

$$
\dot{x}(t)=\mathcal{L}(t) x(t)
$$

has a trichotomy with constants $\alpha \geqslant 1$ and $\sigma>0$.
$\left(\mathrm{M}_{3}\right)$ There exist two real nonnegative functions $c_{1}, c_{2}$ which are locally integrable on $\mathbb{R}$ and, for each $t \in \mathbb{R}$, there exist two constants $C_{1}$ and $C_{2}$ such that

$$
\sup _{t \in \mathbb{R}} \int_{t}^{t+1} c_{1}(s) \mathrm{d} s \leqslant C_{1}, \quad \sup _{t \in \mathbb{R}} \int_{t}^{t+1} c_{2}(s) \mathrm{d} s \leqslant C_{2},
$$

where $0<C_{2}<\frac{1}{2}\left(1-\mathrm{e}^{-\sigma}\right) / \alpha$ and $\|f(t, x)\| \leqslant c_{1}(t)+c_{2}(t)\|x\|$ for each $t \in \mathbb{R}$ and $x \in E$.
$\left(\mathrm{M}_{4}\right)$ For each compact subset $I$ of $\mathbb{R}$ and for each $\varepsilon>0$ there exists a closed subset $I_{\varepsilon}$ of $I$ with $\lambda\left(I-I_{\varepsilon}\right)<\varepsilon$ such that for any nonempty bounded subset $U$ of $E$ one has

$$
\gamma(f(J \times U)) \leqslant \sup _{t \in J} w(t, \gamma(U))
$$

for any compact subset $J$ of $I_{\varepsilon}$.
Then there exists a bounded weak solution of $(\mathrm{P})$ on $\mathbb{R}$.
Proof. By virtue of assumption $\left(\mathrm{M}_{2}\right)$ there exist two constants $\alpha$ and $\sigma$ such that for each $t, s \in \mathbb{R}$,

$$
\begin{equation*}
|K(t, s)| \leqslant \alpha \mathrm{e}^{-\sigma(t-s)} . \tag{2}
\end{equation*}
$$

If $M=2 \alpha C_{1} /\left(1-\mathrm{e}^{-\sigma}-2 \alpha C_{2}\right)$, then $M>0$. Put

$$
\begin{aligned}
H= & \left\{x \in C_{w}(\mathbb{R}, E):\|x(t)\| \leqslant M,\|x(t)-x(\tau)\| \leqslant M \int_{\tau}^{t}|\mathcal{L}(s)| \mathrm{d} s\right. \\
& \left.+\int_{\tau}^{t} c_{1}(s) \mathrm{d} s+M \int_{\tau}^{t} c_{2}(s) \mathrm{d} s, \tau \leqslant t\right\} .
\end{aligned}
$$

$H$ is a nonempty, almost equicontinuous, bounded, closed and convex subset of $C_{w}(\mathbb{R}, E)$. For each $x \in H$ we can define a mapping $\Gamma$ by

$$
\Gamma(x)(t)=\int_{\mathbb{R}} K(t, s) f(s, x(s)) \mathrm{d} s \quad \text { for each } t \in \mathbb{R}
$$

By Lemma (2.4) and (2) we have $\|\Gamma(x)\| \leqslant 2 \alpha\left(C_{1}+M C_{2}\right) /\left(1-\mathrm{e}^{-\sigma}\right)=M$, and so $\Gamma$ is bounded on $\mathbb{R}$. Moreover, since $y=\Gamma(x)$ is a weak solution of the equation $\dot{y}(t)=\mathcal{L}(t) y(t)+f(t, x(t))$, we have

$$
\begin{aligned}
\|\Gamma(x)(t)-\Gamma(x)(\tau)\| & \leqslant \int_{t}^{\tau}\|\mathcal{L}(s) \Gamma(x)(s)+f(t, x(s))\| \mathrm{d} s \\
& \leqslant M \int_{\tau}^{t}|\mathcal{L}(s)| \mathrm{d} s+\int_{\tau}^{t} c_{1}(s) \mathrm{d} s+M \int_{\tau}^{t} c_{2}(s) \mathrm{d} s
\end{aligned}
$$

Therefore $\Gamma(x) \in H$ and $\Gamma: H \rightarrow H$. Moreover, it can be shown as in [7] that $\Gamma$ is continuous on $H$. Now we note that each nonempty subset $X$ of $H$ is equicontinuous. According to the definition of $\gamma$ for each $\varepsilon>0$ there exists $V \in N^{\prime}$ with $p(V)<\varepsilon$. We can find two positive constants $\delta, q$ such that $M \mathrm{e}^{-\delta q}<2 \delta$ and $B_{\delta} \subset V$. In the sequel without loss of generality we will assume that $A=(t-q, t+q)$ and $0 \notin A$. Set $X_{1}=\int_{-\infty}^{t-q} K(t, s) f(s, X(s)) \mathrm{d} s$, thus

$$
\left\|X_{1}\right\| \leqslant \int_{-\infty}^{t-q} \alpha \mathrm{e}^{-\delta(t-s)}\left(c_{1}(s)+M c_{2}(s)\right) \mathrm{d} s \leqslant \frac{M \mathrm{e}^{-\delta q}}{2}<\delta
$$

and $\gamma\left(X_{1}\right) \leqslant p(V) \leqslant \varepsilon$, so $X_{1} \subset B_{\delta} \subset V$. Moreover, from [32] we have

$$
\gamma\left(\int_{t+q}^{\infty} K(t, s) f(s, X(s)) \mathrm{d} s\right) \leqslant \varepsilon
$$

By condition $\left(\mathrm{M}_{4}\right)$ there exists a closed subset $J_{\varepsilon}$ of $[t-q, t+q]$ such that $\lambda([t-q$, $\left.t+q]-J_{\varepsilon}\right)<\varepsilon$ and for any compact subset $K$ of $J_{\varepsilon}$ and any bounded subset $Z$ of $E$,

$$
\begin{equation*}
\gamma(f(K \times Z)) \leqslant \sup _{s \in K} w(s, \gamma(Z)) . \tag{3}
\end{equation*}
$$

By Scorza-Dragoni theorem there exists a closed subset $I_{\varepsilon}$ of the interval $[t-q, v]$ such that $\lambda\left(I-I_{\varepsilon}\right)<\delta$ and there exist $\delta(\varepsilon), \eta>0(\eta<\delta)$ such that $s_{1}, s_{2} \in I_{\varepsilon} ; r_{1}, r_{2} \in[a, b]$ with $\left|s_{1}-s_{2}\right|<\delta,\left|r_{1}-r_{2}\right|<\delta \Rightarrow\left|w\left(s_{1}, r_{1}\right)-w\left(s_{2}, r_{2}\right)\right|<\varepsilon$. Put $D=\{x \in C([t-q, v], E): x \in X\}$, so

$$
\gamma(D)=\sup \{\gamma(X(s)): t-q \leqslant s \leqslant v\} \leqslant \gamma(X)
$$

and

$$
\left|s_{1}-s_{2}\right|<\eta \Rightarrow\left|\gamma\left(D\left(s_{1}\right)\right)-\gamma\left(D\left(s_{2}\right)\right)\right|<\delta .
$$

Let us fix $u, v, t-q \leqslant u<v<t+q$ and let $u=t_{0}<t_{1}<\ldots<t_{m}=v$ be a partition of $[u, v]$ with $t_{i}-t_{i-1}<\eta$ for $i=1, \ldots, m$. Let $T_{i}=J_{\varepsilon} \cap\left[t_{i-1}, t_{i}\right] \cap I_{\varepsilon}$, $P=\bigcup_{i=1}^{m} T_{i}=[u, v] \cap J_{\varepsilon} \cap I_{\varepsilon}$ and $Q=[u, v]-P$. We can find $\eta^{\prime}>0, \eta^{\prime}<\delta$, such that if $r_{1}, r_{2} \in P$ and $\left|r_{1}-r_{2}\right|<\eta^{\prime}$, then

$$
\left|K\left(t, r_{1}\right)-K\left(t, r_{2}\right)\right|<\varepsilon
$$

and we can find $s_{i}$ in $T_{i}$ with

$$
\begin{equation*}
\sup _{s \in T_{i}}|K(t, s)|=\left|K\left(t, s_{i}\right)\right| . \tag{4}
\end{equation*}
$$

Further, we have

$$
\begin{equation*}
\int_{s}^{v} K(t, s) f(s, D(s)) \mathrm{d} s \subset \int_{P} K(t, s) f(s, D(s)) \mathrm{d} s+\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s \tag{5}
\end{equation*}
$$

By the mean value theorem for the Pettis-integral we obtain

$$
\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s \subset \sum_{i=1}^{n} \lambda\left(T_{i}\right) \overline{\operatorname{conv}}\left\{K(t, s) f(s, w): s \in T_{i}, w \in D(s)\right\}
$$

Let $D_{i}=\left\{x(t): x \in D, t \in T_{i}\right\}$. Hence, by Lemma 2.8,

$$
\begin{equation*}
\gamma\left(D_{i}\right)=\sup \left\{\gamma(D(t)): t \in T_{i}\right\}=\gamma\left(D\left(s_{i}^{\prime}\right)\right) \quad \text { for some } s_{i}^{\prime} \in T_{i} . \tag{6}
\end{equation*}
$$

In view of (4), (6) and (3) we have

$$
\gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \sum_{i=1}^{m} \lambda\left(T_{i}\right)\left|K\left(t, s_{i}\right)\right| w\left(q_{i}, \gamma(D(s)), \quad q_{i} \in T_{i}\right.
$$

Moreover, $\left|w(s, \gamma(D(s)))-w\left(q_{i}, \gamma\left(D\left(s_{i}^{*}\right)\right)\right)\right| \leqslant \varepsilon^{\prime} / \lambda(P)$ for all $s^{*} \in T_{i}$. So

$$
\lambda\left(T_{i}\right)\left|K\left(t, s_{i}\right)\right| w\left(q_{i}, \gamma\left(D\left(s_{i}^{*}\right)\right)\right) \leqslant \int_{T_{i}}|K(t, s)| w(s, \gamma(D(s))) \mathrm{d} s+\frac{\varepsilon^{\prime} \lambda\left(T_{i}\right)}{\lambda(P)}
$$

and
(7) $\quad \gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \sum_{i=1}^{m}\left(\int_{T_{i}}|K(t, s)| w(s, \gamma(D(s))) \mathrm{d} s+\frac{\varepsilon^{\prime} \lambda\left(T_{i}\right)}{\lambda(P)}\right)$

$$
=\int_{P}|K(t, s)| w(s, \gamma(D(s))) \mathrm{d} s+\varepsilon^{\prime} .
$$

Furthermore, we have

$$
\begin{equation*}
\gamma\left(\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \int_{Q}|K(t, s)|\left(c_{1}(s)+M c_{2}(s)\right) \mathrm{d} s \tag{8}
\end{equation*}
$$

From (5) we have

$$
\begin{aligned}
\gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant & \gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) \\
& +\gamma\left(\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s\right) .
\end{aligned}
$$

If $\lambda(Q)<\varepsilon$, then from (7) and (8) we deduce that

$$
\begin{aligned}
\gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) & \leqslant \int_{P}\|K(t, s)\| w(s, \gamma(D(s))) \mathrm{d} s \\
& \leqslant \int_{u}^{v}|K(t, s)| w(s, \gamma(D(s))) \mathrm{d} s
\end{aligned}
$$

Moreover,

$$
\gamma(\varphi(D)(v)) \leqslant \gamma(\varphi(D)(u))+\gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) .
$$

Defining $\varrho(t):=\gamma(D(t))$ we get

$$
\varrho(v)-\varrho(u) \leqslant \gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \gamma\left(B_{1}\right) \int_{u}^{v}|K(t, s)| w(s, \varrho(s)) \mathrm{d} s
$$

Therefore $\dot{\varrho}(t) \leqslant \alpha \gamma\left(B_{1}\right) \mathrm{e}^{-\sigma(t-s)} w(t, \varrho(t))$ a.e. on $[u, v]$ and since $\varrho(u)=0$, hence $\varrho \equiv 0$ and so $\bar{D}^{w}$ is weakly compact in $C_{w}(\mathbb{R}, E)$. But $D$ is closed, hence it is a convex and compact subset in $C_{w}(\mathbb{R}, E)$. By the Schauder-Tichonov theorem, since $\varphi$ is a continuous mapping from $D$ to $D$, there is a fixed point $y$ of $\varphi$ such that $y$ is the desired weak solution of $(\mathrm{P})$.

Theorem 3.2. Let the following assumptions be fulfilled:
$\left(\mathrm{A}_{1}\right) \mathcal{L}: \mathbb{R} \rightarrow L(E)$ is strongly measurable and Bochner integrable on every finite subinterval of $\mathbb{R}$ and the linear equation

$$
\dot{x}(t)=\mathcal{L}(t) x(t)
$$

has a trichotomy with constants $\alpha \geqslant 1$ and $\sigma>0$.
$\left(\mathrm{A}_{2}\right) f: \mathbb{R} \times E \rightarrow E$ is a function such that
(i) for each $t \in \mathbb{R}$ the function $f(t,$.$) is continuous,$
(ii) for each $x \in E$ the function $f(\cdot, x)$ is measurable,
(iii) there exist two real nonnegative functions $c_{1}, c_{2}$ locally integrable on $\mathbb{R}$ and, for each $t \in \mathbb{R}$, two constants $C_{1}$ and $C_{2}$ with

$$
\sup _{t \in \mathbb{R}} \int_{t}^{t+1} c_{1}(s) \mathrm{d} s \leqslant C_{1}, \quad \sup _{t \in \mathbb{R}} \int_{t}^{t+1} c_{2}(s) \mathrm{d} s \leqslant C_{2},
$$

where $0<C_{2}<\left(1-\mathrm{e}^{-\sigma}\right) / 2 \alpha$ and $\|f(t, x)\| \leqslant c_{1}(t)+c_{2}(t)\|x\|$ for each $t \in \mathbb{R}$ and $x \in E$.
$\left(\mathrm{A}_{3}\right) h: \mathbb{R} \times[0, \infty) \rightarrow \mathbb{R}^{+}$satisfies the Carathéodory conditions.
$\left(\mathrm{A}_{4}\right) L=\sup \left\{\int_{A}\|K(t, s)\| h(t, \gamma(B(s)) \mathrm{d} s: t \in \mathbb{R}\} \leqslant \sup \{\gamma(B(s)): s \in A\}\right.$, where $B$ is a bounded subset of $C(\mathbb{R}, E)$, for each compact subset $A$ of $\mathbb{R}$.
$\left(\mathrm{A}_{5}\right)$ For each compact subset $I$ of $\mathbb{R}$ and for each $\varepsilon>0$, there exists a closed subset $I_{\varepsilon}$ of $I$ with $\lambda\left(I-I_{\varepsilon}\right)<\varepsilon$ such that for any nonempty bounded subset $U$ of $E$ one has

$$
\gamma(f(J \times U)) \leqslant \sup _{t \in J} h(t, \gamma(U))
$$

for any compact subset $J$ of $I_{\varepsilon}$.
Then there is at least one bounded solution of $(\mathrm{P})$ on $\mathbb{R}$.
Proof. By the assumption $\left(\mathrm{A}_{1}\right)$ there exist two constants $\alpha$ and $\sigma$ such that for each $t, s \in \mathbb{R}$, [11] Lemma 7 yields

$$
\begin{equation*}
|K(t, s)| \leqslant \alpha \mathrm{e}^{-\sigma(t-s)} \tag{9}
\end{equation*}
$$

Now if $M=2 \alpha C_{1} /\left(1-\mathrm{e}^{-\sigma}-2 \alpha C_{2}\right)$, then $M>0$. Put

$$
\begin{aligned}
H=\{ & x \in C(\mathbb{R}, E):\|x(t)\| \leqslant M,\|x(t)-x(\tau)\| \leqslant M \int_{\tau}^{t}|A(s)| \mathrm{d} s \\
& \left.+\int_{\tau}^{t} c_{1}(s) \mathrm{d} s+M \int_{\tau}^{t} c_{2}(s) \mathrm{d} s, \tau \leqslant t\right\} .
\end{aligned}
$$

$H$ is a nonempty, almost equicontinuous, bounded, closed and convex subset of $C(\mathbb{R}, E)$. For each $x \in H$ we can define a mapping $\psi$ by

$$
\psi(x)(t)=\int_{\mathbb{R}} K(t, s) f(s, x(s)) \mathrm{d} s \quad \text { for each } t \in \mathbb{R}
$$

and this mapping is bounded on $\mathbb{R}$. Since $y=\psi(x)$ is a solution of the equation $\dot{y}=A(t) y+f(t, x(t))$, we have

$$
\begin{aligned}
\|\psi(x)(t)-\psi(x)(\tau)\| & \leqslant \int_{t}^{\tau}\|A(s) \psi(x)(s)+f(t, x(s))\| \mathrm{d} s \\
& \leqslant M \int_{\tau}^{t}|A(s)| \mathrm{d} s+\int_{\tau}^{t} c_{1}(s) \mathrm{d} s+M \int_{\tau}^{t} c_{2}(s) \mathrm{d} s
\end{aligned}
$$

By Lemma (2.4) and (9)

$$
\|\psi(x)\| \leqslant \frac{2 \alpha\left(C_{1}+M C_{2}\right)}{1-\mathrm{e}^{-\sigma}}=M
$$

Therefore $\psi(x) \in H$ and $\psi: H \rightarrow H$. Moreover, it can be shown as in [7] that $\psi$ is a continuous function on $H$. Now we note that each subset $X$ of $H$ is equicontinuous. By the definition of $\gamma$ for each $\varepsilon>0$ there exists $V \in N^{\prime}$ with $p(V)<\varepsilon$. We can find two positive constants $\delta, q$ such that $M \mathrm{e}^{-\delta q}<2 \delta$ and $B_{\delta} \subset V$. In the sequel without loss of generality we will assume that $A=(t-q, t+q)$ and $0 \notin A$. Set $X_{1}=$ $\int_{-\infty}^{t-q} K(t, s) f(s, X(s)) \mathrm{d} s,\left\|X_{1}\right\| \leqslant \int_{-\infty}^{t-q} \alpha \mathrm{e}^{-\delta(t-s)}\left(c_{1}(s)+M c_{2}(s)\right) \mathrm{d} s \leqslant M \mathrm{e}^{-\delta q} / 2<\delta$ and

$$
\gamma\left(X_{1}\right) \leqslant p(V) \leqslant \varepsilon
$$

Thus $X_{1} \subset B_{\delta} \subset V$. Moreover [32],

$$
\gamma\left(\int_{t+q}^{\infty} K(t, s) f(s, X(s)) \mathrm{d} s\right) \leqslant \varepsilon
$$

Condition $\left(\mathrm{M}_{5}\right)$ yields that there exists a closed subset $J_{\varepsilon}$ of $[t-q, t+q]$ such that $\lambda\left([t-q, t+q]-J_{\varepsilon}\right)<\varepsilon$ and for any compact subset $K$ of $J_{\varepsilon}$ and any bounded subset $Z$ of $E$,

$$
\begin{equation*}
\gamma(f(K \times Z)) \leqslant \sup _{s \in K} h(s, \gamma(Z)) . \tag{10}
\end{equation*}
$$

From the Scorza-Dragoni theorem there exists a closed subset $I_{\varepsilon}$ of the interval $[t-q, t+q]$ such that $\lambda\left(I-I_{\varepsilon}\right)<\delta$ and there exist $\delta(\varepsilon), \eta>0, \eta<\delta$, such that $s_{1}, s_{2} \in I_{\varepsilon} ; r_{1}, r_{2} \in[a, b]$ with $\left|s_{1}-s_{2}\right|<\delta,\left|r_{1}-r_{2}\right|<\delta \Rightarrow\left|h\left(s_{1}, r_{1}\right)-h\left(s_{2}, r_{2}\right)\right|<\varepsilon$. Put $D=\{X(s): t-q \leqslant s \leqslant t+q\}$, so

$$
\gamma(D)=\sup \{\gamma(X(s)): t-q \leqslant s \leqslant t+s\} \leqslant \gamma(X)
$$

and

$$
\left|s_{1}-s_{2}\right|<\eta \Rightarrow\left|\gamma\left(D\left(s_{1}\right)\right)-\gamma\left(D\left(s_{2}\right)\right)\right|<\delta
$$

Let $t-q=t_{0}<t_{1}<\ldots<t_{m}=t+q$ be a partition of $[t-q, t+q]$ with $t_{i}-t_{i-1}<\eta$ for $i=1, \ldots, m$. Let $T_{i}=J_{\varepsilon} \cap\left[t_{i-1}, t_{i}\right] \cap I_{\varepsilon}, P=\bigcup_{i=1}^{m} T_{i}=[t-q, t+q] \cap J_{\varepsilon} \cap I_{\varepsilon}$ and $Q=[t-q, t+q]-P$. We can find $\eta^{\prime}>0\left(\eta^{\prime}<\delta\right)$ such that if $r_{1}, r_{2} \in P$ and $\left|r_{1}-r_{2}\right|<\eta^{\prime}$, then

$$
\left|K\left(t, r_{1}\right)-K\left(t, r_{2}\right)\right|<\varepsilon,
$$

and we can find $s_{i}$ in $T_{i}$ with

$$
\begin{equation*}
\sup _{s \in T_{i}}|K(t, s)|=\left|K\left(t, s_{i}\right)\right| . \tag{11}
\end{equation*}
$$

Further, we have

$$
\begin{align*}
\int_{t-q}^{t+q} K(t, s) f(s, D(s)) \mathrm{d} s \subset & \int_{P} K(t, s) f(s, D(s)) \mathrm{d} s  \tag{12}\\
& +\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s
\end{align*}
$$

By the mean value theorem for the Pettis-integral we obtain

$$
\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s \subset \sum_{i=1}^{n} \lambda\left(T_{i}\right) \overline{\overline{\operatorname{conv}}\left\{K(t, s) f(s, w): s \in T_{i}, w \in D(s)\right\} . . . ~ . ~}
$$

Let $D_{i}=\left\{x(t): x \in D, t \in T_{i}\right\}$. Hence, by Lemma 2.8,

$$
\begin{equation*}
\gamma\left(D_{i}\right)=\sup \left\{\gamma(D(t)): t \in T_{i}\right\}=\gamma\left(D\left(s_{i}^{\prime}\right)\right) \quad \text { for some } s_{i}^{\prime} \in T_{i} \tag{13}
\end{equation*}
$$

In view of (11), (13) and (10) we have

$$
\gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \sum_{i=1}^{m} \lambda\left(T_{i}\right)\left|K\left(t, s_{i}\right)\right| h\left(q_{i}, \gamma(D(s)), \quad q_{i} \in T_{i} .\right.
$$

Moreover, $\left|h(s, \gamma(D(s)))-h\left(q_{i}, \gamma\left(D\left(s_{i}^{*}\right)\right)\right)\right| \leqslant \varepsilon^{\prime} / \lambda(P)$ for all $s^{*} \in T_{i}$. So

$$
\lambda\left(T_{i}\right)\left|K\left(t, s_{i}\right)\right| h\left(q_{i}, \gamma\left(D\left(s_{i}^{*}\right)\right)\right) \leqslant \int_{T_{i}}|K(t, s)| h(s, \gamma(D(s))) \mathrm{d} s+\frac{\varepsilon^{\prime} \lambda\left(T_{i}\right)}{\lambda(P)}
$$

and

$$
\begin{align*}
\gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) & \leqslant \sum_{i=1}^{m}\left(\int_{T_{i}}|K(t, s)| h(s, \gamma(D(s))) \mathrm{d} s+\frac{\varepsilon^{\prime} \lambda\left(T_{i}\right)}{\lambda(P)}\right)  \tag{14}\\
& =\int_{P}|K(t, s)| h(s, \gamma(D(s))) \mathrm{d} s+\varepsilon^{\prime}
\end{align*}
$$

Furthermore, we have

$$
\begin{equation*}
\gamma\left(\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \int_{Q}|K(t, s)|\left(c_{1}(s)+M c_{2}(s)\right) \mathrm{d} s \tag{15}
\end{equation*}
$$

From (12) we have

$$
\begin{aligned}
\gamma\left(\int_{t-q}^{t+q} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant & \gamma\left(\int_{P} K(t, s) f(s, D(s)) \mathrm{d} s\right) \\
& +\gamma\left(\int_{Q} K(t, s) f(s, D(s)) \mathrm{d} s\right)
\end{aligned}
$$

If $\lambda(Q)<\varepsilon$, then from (14) and (15) we deduce that

$$
\begin{aligned}
\gamma\left(\int_{t-q}^{t+q} K(t, s) f(s, D(s)) \mathrm{d} s\right) & \leqslant \int_{P}|K(t, s)| h(s, \gamma(D(s))) \mathrm{d} s \\
& \leqslant \int_{t-q}^{t+q}|K(t, s)| h(s, \gamma(D(s))) \mathrm{d} s \\
& \leqslant \sup \{\gamma(D(s)): t-q<s<t+q\}=\gamma(D)
\end{aligned}
$$

Thus

$$
\gamma(\psi(X(t))) \leqslant 2 \varepsilon+\gamma(D) \leqslant 2 \varepsilon+\gamma(X)
$$

If we put $\aleph(X)=\sup \{\gamma(X(t)): t \in \mathbb{R}\}$ then, by Lemma 2.6, $\aleph$ satisfies the condition $\left(\mathrm{M}_{5}\right)$ in Lemma 2.1 and moreover $\aleph(\psi(X)) \leqslant \aleph(X)$. By Theorem $2.9 \psi$ has a fixed point in $H$ which, due to Lemma 7 of [12], is a bounded solution of (P).

In the next theorem we will deal with the differential equation

$$
\dot{x}(t)=\mathcal{L}(t) x(t)+f^{\prime}(t, x(t)), \quad t \in \mathbb{R}
$$

where $f^{\prime}: \mathbb{R} \times E \rightarrow E$ is a Carathéodory function, $\mathcal{L}: \mathbb{R} \rightarrow L(E)$ is a strongly measurable and Bochner integrable operator on every closed finite interval $I$ of $\mathbb{R}$ and $\gamma$ is a $(K, N, p)$-measure of weak noncompactness. The Kuratowski measure of noncompactness is a $(K, N, p)$-measure of noncompactness [5], [1], hence we get generalizations of results such as Theorem 2 in [37] and Theorem 9 in [14].

Theorem 3.3. Assume that $f^{\prime}: \mathbb{R} \times E \rightarrow E$ satisfies $\left(\mathrm{M}_{3}\right)$ and $\left(\mathrm{M}_{4}\right)$ of Theorem 3.1 while $\mathcal{L}: \mathbb{R} \rightarrow L(E)$ is a strongly measurable and Bochner integrable operator on every closed finite interval I of $\mathbb{R}$. Moreover, assume
(i) for each $t \in \mathbb{R}, f^{\prime}(t, \cdot)$ is continuous,
(ii) for each $x \in E, f^{\prime}(\cdot, x)$ is measurable,
(iii) for each $x \in E$ and each closed finite interval $I$ of $\mathbb{R}, f^{\prime}(I \times\{x\})$ is separable.

Then problem ( $\mathrm{P}^{\prime}$ ) has at least one bounded solution.

Proof. Let

$$
\begin{aligned}
W=\{ & x \in C(\mathbb{R}, E):\|x(t)\| \leqslant M,\|x(t)-x(\tau)\| \leqslant M \int_{\tau}^{t}|\mathcal{L}(s)| \mathrm{d} s \\
& \left.+\int_{\tau}^{t} c_{1}(s) \mathrm{d} s+M \int_{\tau}^{t} c_{2}(s) \mathrm{d} s, \tau \leqslant t\right\} .
\end{aligned}
$$

We can define a mapping $\psi: W \rightarrow W$ by

$$
\psi(x)(t)=\int_{\mathbb{R}} K(t, s) f(s, x(s)) \mathrm{d} s \quad \text { for each } t \in \mathbb{R}
$$

Let $x_{0}$ be an arbitrary element in $W, \psi\left(x_{n}\right)=x_{n+1}$ and $Y=\left\{x_{n}: n=0,1,2,3, \ldots\right\}$. As in the proof of Theorem 3.1, there exist two constant $u, v$ such that if $V=\left\{x_{n} \in\right.$ $\left.C([t-q, v], E): x_{n} \in Y\right\}$ and we define $\varrho(t):=\gamma(V(t))$, then

$$
\varrho(v)-\varrho(u) \leqslant \gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \gamma\left(B_{1}\right) \int_{u}^{v}|K(t, s)| w(s, \varrho(s)) \mathrm{d} s
$$

Therefore $\dot{\varrho}(t) \leqslant \alpha \gamma\left(B_{1}\right) \mathrm{e}^{-\sigma(t-s)} w(t, \varrho(t))$ a.e. on $[u, v]$ and since $\varrho(u)=0$, we have $\varrho \equiv 0$. Thus the closure of $V$ is compact and so we can find a subsequence $\left(x_{n_{k}}\right)$ of $\left(x_{n}\right)$ which converges to a limit $x$. Since $\left\|x_{n}-\varphi\left(x_{n}\right)\right\| \rightarrow 0$ as $n \rightarrow \infty$ and $\varphi$ is continuous, hence $x=\varphi(x)$ so that $x$ is the desired solution of ( $\mathrm{P}^{\prime}$ ).

We are in a position to prove the following result.
Theorem 3.4. Let $\mathfrak{h}:[a, b] \times \mathbb{R}^{a} \rightarrow \mathbb{R}^{+}$be a Carathéodry function and, for each bounded subset $Z$ of $[a, b] \times \mathbb{R}^{a}$, let there exist a measurable function $m_{Z}$ such that $\mathfrak{h}(t, s) \leqslant m_{Z}(t)$ for each $(t, s) \in Z$ and $m$ is integrable on $[c, T]$ for each $c$; $a<c \leqslant b$. Moreover, let for each $c$; $a<c \leqslant b$, the identically zero function be the only absolutely continuous function on $[a, c]$ which satisfies $\dot{u}(t)=\mathfrak{h}(t, u(t))$ a.e. on $[a, c]$, such that the right hand derivative of $u(t)$ at $t=a, D_{+} u(a)$, exists and $D_{+} u(a)=u(a)=0$. If we replace in the setting of Theorem 3.3 a Kamke function $w$ by a function $\mathfrak{h}$ and suppose that $f^{\prime}$ is bounded and continuous, then the problem (P) has at least one solution.

Proof. Due to the assumption that $f^{\prime}$ is bounded we can find a constant $C$ such that $\left\|f^{\prime}(t, x)\right\| \leqslant C$. Let $\mathcal{L}:[a, b] \rightarrow \mathbb{R}$ be defined by

$$
\mathcal{L}(t)=\sup _{\|x\|,\|y\| \leqslant C t}\left\|f^{\prime}(t, x)-f^{\prime}(t, y)\right\| .
$$

It can be shown as in [14], [29], that $\mathcal{L}$ is continuous at $a$ and lower semicontinuous on $] a, b]$. Consequently, we can say that $\left\|\int_{t}^{\tau} f^{\prime}(s, x(s))-\int_{t}^{\tau} f^{\prime}(s, y(s)) \mathrm{d} s\right\| \leqslant \int_{t}^{\tau} \mathcal{L}(s) \mathrm{d} s$
for each $x, y \in Y$. Now by the same argument as in the proof of Theorem 3.3 if we put $Y=\left\{x_{n}: n=0,1,2,3, \ldots\right\}$ and $V=\left\{x_{n} \in C([t-q, v], E): x_{n} \in Y\right\}$ while $\varrho(t)=\gamma(V(t))$ we get

$$
\varrho(v)-\varrho(u) \leqslant \gamma\left(\int_{u}^{v} K(t, s) f(s, D(s)) \mathrm{d} s\right) \leqslant \gamma\left(B_{1}\right) \int_{u}^{v}|K(t, s)| w(s, \varrho(s)) \mathrm{d} s
$$

Now we can conclude that

$$
\varrho(\tau)-\varrho(t) \leqslant \min \left(\int_{t}^{\tau} \mathcal{L}(s) \mathrm{d} s, \gamma\left(B_{1}\right) \int_{t}^{\tau} K(t, s) f(s, D(s)) \mathrm{d} s\right), \quad t-q<t \leqslant \tau \leqslant v
$$

Since $\varrho$ is an absolutely continuous function on $[t-q, v]$ so

$$
\begin{equation*}
\dot{\varrho}(t) \leqslant \min \left(\mathcal{L}(t), \gamma\left(B_{1}\right) \alpha f(t, D(t)), \quad \text { a.e. on }[t-q, v] .\right. \tag{16}
\end{equation*}
$$

By Lemma 1 in $[29] \varrho \equiv 0$ on $[t-q, v]$ and thus we obtain the result.

## 4. Existence results for problem (Q)

For $t \in[a, b]$ we let $\widehat{\mathcal{L}}(t) \in L(E)$ and $\tau_{t} x(s)=x(t+s)$ for all $s \in[-d, 0]$. Assume that $C([-d, 0], E)$ is the Banach space of continuous functions from $[-d, 0]$ into $E$ and $f^{d}:[a, b] \times C([-d, 0], E) \rightarrow E$. In the next theorem we deal with the problem

$$
\begin{equation*}
\dot{x}(t)=\widehat{\mathcal{L}}(t) x(t)+f^{d}\left(t, \tau_{t} x\right), \quad t \in[a, b] \tag{Q}
\end{equation*}
$$

and obtain a generalization of Theorem 3.1.
Theorem 4.1. We assume:
$\left(\mathrm{H}_{1}\right) f^{d}:[a, b] \times C_{(w)}([-d, 0], E) \rightarrow E$ is continuous, where $C_{(w)}([-d, 0], E)$ is the space of all weakly continuous functions from $[-d, 0]$ to $E$.
$\left(\mathrm{H}_{2}\right) \widehat{\mathcal{L}}:[a, b] \rightarrow L(E)$ is a strongly measurable and Bochner integrable operator on $[a, b]$ and the linear equation

$$
\dot{x}(t)=\widehat{\mathcal{L}}(t) x(t)
$$

has a trichotomy with constants $\alpha \geqslant 1$ and $\sigma>0$.
$\left(\mathrm{H}_{3}\right)$ There exist two real nonnegative functions $c_{1}, c_{2}$ integrable on $[a, b]$ and two constants $C_{1}$ and $C_{2}$ such that

$$
\int_{a}^{b} c_{1}(s) \mathrm{d} s \leqslant C_{1}, \quad \int_{a}^{b} c_{2}(s) \mathrm{d} s \leqslant C_{2}
$$

where $0<C_{2}<\frac{1}{2}\left(1-\mathrm{e}^{-\sigma}\right) / \alpha$ and $\|f(t, \varphi)\| \leqslant c_{1}(t)+c_{2}(t)\|\varphi(0)\|$ for each $t \in[a, b]$ and $\varphi \in C([-d, 0], E)$.
$\left(\mathrm{H}_{4}\right)$ For each $\varepsilon>0$ there exists a closed subset $I_{\varepsilon}$ of $[a, b]$ with $\lambda\left([a, b]-I_{\varepsilon}\right)<\varepsilon$ such that for any nonempty bounded subset $A$ of $C([-d, 0], E)$ and for each closed subset $J \subseteq I_{\varepsilon}$, one has

$$
\gamma(F(J \times A)) \leqslant \sup _{t \in J} h(t, \gamma(A(0))) .
$$

Then, for each $\psi \in C_{E}([a-d, a])$ such that $\psi(a)=0$, the problem (Q) has a weak solution on the interval $[a-d, b]$.

Proof. Along the same lines as in [17], [18], [16] we use some methods for functional equations. We partition the closed interval $[a, b]$ by the points $t_{i}^{n}=$ $(i b+(n-i) a) / n$ where $i=0,1,2, \ldots, n$. Let $\xi_{1}^{n}:\left[a-d, t_{1}^{n}\right] \times E \rightarrow E$ be a function defined by

$$
\xi_{1}^{n}(t, x)= \begin{cases}\psi(t) & \text { if } t \in[a-d, a] \\ n(t-a) x & \text { if } t \in\left[a, t_{1}^{n}\right]\end{cases}
$$

where $n$ is a positive integer. Let $f_{1}^{n}:\left[a, t_{1}^{n}\right] \times E \rightarrow E$ be a function defined by $f_{1}^{n}(t, x)=f^{d}\left(t, \tau_{t_{1}^{n}}\left(\xi_{1}^{n}(\cdot, x)\right)\right)$. Due to Theorem 3.1 there is a function $v_{n}$ such that $v_{n}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{1}^{n}\right]$

$$
v_{n}(t)=\int_{a}^{t} K(t, s) f_{1}^{n}\left(s, v_{n}(s)\right) \mathrm{d} s
$$

Moreover, there exists a function $u_{n}:\left[-d, t_{k}^{n}\right] \rightarrow E$ defined by $u_{n}=\psi$ on $[a-d, a]$ and

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{k}^{n}\left(s, u_{n}(s)\right) \mathrm{d} s, \quad t \in\left[a, t_{k}^{n}\right]
$$

where $f_{k}^{n}(t, x)=f^{d}\left(t, \tau_{t_{k}^{n}} \xi_{n}^{k}(\cdot, x)\right)$ and $\xi_{k}^{n}:\left[a-d, t_{k}^{n}\right] \times E \rightarrow E$ is defined by

$$
\xi_{k}^{n}(t, x)= \begin{cases}u_{n}(t) & \text { if } t \in\left[a-d, t_{k-1}^{n}\right], \\ u_{n}\left(t_{k-1}^{n}\right)+n\left(t-t_{k-1}^{n}\right)\left(x-u_{n}\left(t_{k-1}^{n}\right)\right) & \text { if } t \in\left[t_{k-1}^{n}, t_{k}^{n}\right]\end{cases}
$$

Assume that $\xi_{k+1}^{n}:\left[a-d, t_{k+1}^{n}\right] \times E \rightarrow E$ is a function defined by

$$
\xi_{k+1}^{n}(t, x)= \begin{cases}u_{n}(t) & \text { if } t \in\left[a-d, t_{k}^{n}\right] \\ u_{n}\left(t_{k}^{n}\right)+n\left(t-t_{k}^{n}\right)\left(x-u_{n}\left(t_{k}^{n}\right)\right) & \text { if } t \in\left[t_{k}^{n}, t_{k+1}^{n}\right]\end{cases}
$$

Let $f_{k+1}^{n}:\left[a, t_{k+1}^{n}\right] \times E \rightarrow E$ be defined by $f_{k+1}^{n}(t, x)=f^{d}\left(t, \tau_{t_{k+1}^{n}}^{n}\left(\xi_{k+1}^{n}(\cdot, x)\right)\right)$. According to Theorem 3.1 there exists a function $u_{n}^{k+1}:\left[a, t_{k+1}^{n}\right] \xrightarrow{k+1} E$ such that for each $t \in\left[a, t_{k+1}^{n}\right]$

$$
u_{n}^{k+1}(t)=\int_{a}^{t} K(t, s) f_{k+1}^{n}\left(s, u_{n}^{k+1}(s)\right) \mathrm{d} s
$$

Put $u_{n}=u_{n}^{k+1}$ on $\left[t_{k}^{n}, t_{k+1}^{n}\right]$. Then we can consider $u_{n}$ is defined on $\left[a-d, t_{k+1}^{n}\right]$ so that $u_{n}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{k+1}^{n}\right]$

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{k+1}^{n}\left(s, u_{n}(s)\right) \mathrm{d} s
$$

Therefore for each $n \in \mathbb{N}$, there exists a continuous function $u_{n}$ such that $u_{n}=\psi$ on $[a-d, a]$ and for each $t \in[a, b]$

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f^{d}\left(s, \tau_{t_{k}^{n}} \xi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right) \mathrm{d} s
$$

where $k \in\{1,2,3, \ldots, n\}$ and $t_{k-1}^{n} \leqslant t \leqslant t_{k}^{n}$. Set $H=\left\{u_{n}: n \in \mathbb{N}\right\}$. If $t_{1}, t_{2} \in[a, b]$ and $t_{1}<t_{2}$, then

$$
\begin{aligned}
\left\|u_{n}\left(t_{1}\right)-u_{n}\left(t_{2}\right)\right\| \leqslant & \int_{a}^{t_{1}}\left|K\left(t_{1}, s\right)-K\left(t_{2}, s\right)\right|\left\|f^{d}\left(s, \tau_{t_{k}^{n}} \xi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)\right\| \mathrm{d} s \\
& +\int_{t_{1}}^{t_{2}}\left|K\left(t_{2}, s\right)\right|\left\|f^{d}\left(s, \tau_{t_{k}^{n}} \xi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)\right\| \mathrm{d} s \\
\leqslant & \int_{a}^{t_{1}}\left|K\left(t_{1}, s\right)-K\left(t_{2}, s\right)\right|\left(c_{1}(s)+c_{2}(s)\left\|u_{n}(s)\right\|\right) \mathrm{d} s \\
& +\alpha \int_{t_{1}}^{t_{2}} \mathrm{e}^{-\sigma\left|t_{2}-s\right|}\left(c_{1}(s)+c_{2}(s)\left\|u_{n}(s)\right\|\right) \mathrm{d} s
\end{aligned}
$$

Furthermore, $|K(t, s)| \leqslant \alpha \mathrm{e}^{-\sigma|t-s|}$ and $u_{n}=\psi$ on $[a-d, a]$; hence, $H$ is equicontinuous in $C([a-d, b], E)$. Moreover, we can define a mapping $\psi^{\prime}$ by

$$
\psi^{\prime}(x)(t)=\int_{a}^{t} K(t, s) f^{d}\left(s, \tau_{t_{k}^{n}} \xi_{k}^{n}(\cdot, x(s))\right) \mathrm{d} s \quad \text { for each } t \in[a, b]
$$

so $\psi^{\prime}(H(t))=\psi^{\prime}\left(\left\{u_{n}(t): n \in \mathbb{N}\right\}\right)$ and $\psi(H(a))=0$.
We can show that $\gamma\left(\psi^{\prime}(H(t))\right)=0$ for all $t \in[a, b]$. Let $a \leqslant t<x \leqslant b$. In the same way as in the proof of Theorem 3.1 if we replace the interval $[t-q, t+q]$ by $[t, x]$ and the set $D$ by $H$, then

$$
\gamma\left(\psi^{\prime}(H(t))\right) \leqslant \int_{t}^{x}|K(t, s)| w(s, \gamma(H(s))) \mathrm{d} s
$$

Define $\varrho(t):=\gamma(H(t))$; since $\gamma(H(t))=\gamma\left(\psi^{\prime}(H(t))\right)$, so $\varrho(a)=0$ and

$$
\varrho(x)-\varrho(t) \leqslant \int_{t}^{x}|K(t, s)| w(s, \varrho(s)) \mathrm{d} s
$$

Therefore $\dot{\varrho}(t) \leqslant \alpha \mathrm{e}^{-\sigma|t-s|} w(t, \varrho(t))$ a.e., thus $\varrho \equiv 0$. By Ascoli's theorem the sequence $\left(u_{n}\right)_{n \in \mathbb{N}}$ converges weakly uniformly to a function $u \in C_{E}([a-d, b], E)$ such that $u=\psi$ on $[a-d, a]$. For simplicity we will denote the function $f^{d}(s$, $\left.\tau_{t_{k}^{n}} \xi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)$ by $h_{n}^{k}(s)$ and we have $\xi\left(\left\{h_{n}^{k}(t): n \in \mathbb{N}\right\}\right)=0$, so $\left\{h_{n}^{k}(t): n \in \mathbb{N}\right\}$ is relatively weakly compact. If we create a multivalued function $F(t)=\overline{\operatorname{conv}}\left\{h_{n}^{k}(t)\right.$ : $n \in \mathbb{N}\}$, then $F(t)$ is nonempty convex and weakly compact. The set

$$
\delta_{F}^{1}:=\left\{l \in L^{1}(I, E): l(t) \in F(t)\right\}
$$

is nonempty convex and weakly compact, thus by the Eberlein-Śmulian theorem there exists a subsequence $\left(h_{n_{j}}^{k}\right)$ of $\left(h_{n}^{k}\right)$ such that $h_{n_{j}}^{k} \rightarrow l$ weakly, $l \in \delta_{F}^{1}$. Thus $u_{n}$ tends weakly to $\int_{a}^{t} K(t, s) l(s) \mathrm{d} s$. Moreover, $u_{n} \in C_{E}([a-d, b])$ and $\left(u_{n}\right)_{n \in \mathbb{N}}$ converges uniformly to $u$ on each compact subset of $[a-d, b]$ and $u$ is uniformly continuous on $[a-d, a]$. But for each $t \in[a, b]$ we can find $n \in \mathbb{N}$ such that $d>(b-a) / n$ and $t \in\left[t_{k-1}^{n}, t_{k}^{n}\right]$ for some $k$ in the set $\{1,2, \ldots, n\}$. Moreover,

$$
\begin{aligned}
&\left\|\tau_{t_{k}^{n}} \xi_{k}^{n}\left(\cdot, u_{n}(t)\right)-\tau_{t} u\right\| \leqslant \sup _{s \in[-d,(a-b) / n]}[ {\left[\left\|\xi_{k}^{n}\left(t_{k}^{n}+s, u_{n}(t)\right)-u\left(t_{k}^{n}+s\right)\right\|\right.} \\
&\left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
&+\sup _{s \in[(a-b) / n, 0]}[ {\left[\left(\| u_{n}\left(t_{k-1}^{n}\right)+n\left(t_{k}^{n}+s-t_{k-1}^{n}\right)\right.\right.} \\
&\left.\times\left(u_{n}(t)-u_{n}\left(t_{k-1}^{n}\right)\right)-u\left(t_{k}^{n}+s\right) \|\right) \\
&\left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
& \leqslant \sup _{s \in[-d,(a-b) / n]}\left[\left\|u_{n}\left(t_{k}^{n}+s\right)-u\left(t_{k}^{n}+s\right)\right\|\right. \\
&\left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
&+\sup _{s \in[(a-b) / n, 0]}\left[\left((b-a)\left\|\left(u_{n}(t)-u_{n}\left(t_{k-1}^{n}\right)\right)\right\|\right.\right. \\
&+\left\|u_{n}\left(t_{k-1}^{n}\right)-u\left(t_{k}^{n}+s\right)\right\| \\
&\left.\left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right)\right] \rightarrow 0 \quad \text { as } n \rightarrow \infty .
\end{aligned}
$$

Thus by Lemma 2.7 we conclude that $u(\cdot)$ is the desired solution of (Q).
There are really only a few results dealing with weak solutions for delayed problems and the proposed one seems to be interesting in this subject. The results presented here are of a more general form (quasi-linear problem and much better
compactness-type assumption). In the important case $\widehat{\mathcal{L}}(t) \equiv 0$ Theorem 4.1 generalizes Theorem 2.10. In [3] the authors formulated a suggestion how to apply the results presented in this paper to retarded lattice dynamical systems.

In the next theorem we use a $(K, N, p)$-measure of weak noncompactness. The Kuratowski measure of noncompactness is ( $K, N, p$ )-measure of weak noncompactness, see [5], [1]; hence, we get generalizations of results so we have a generalization for Theorem 3.3 and improvement for Theorem 2 in [37] and Theorem 9 in [14]. In the following theorem we have a finite delay and we obtain similar result to that for problem (P).

Theorem 4.2. We assume:
$\left(\mathrm{H}_{1}\right) f^{d}:[a, b] \times C_{E}([-d, 0]) \rightarrow E$ is a function such that
(i) $t \mapsto f^{d}(t, \varphi)$ is measurable,
(ii) $\varphi \mapsto f^{d}(t, \varphi)$ is continuous,
(iii) there exist two real nonnegative functions $c_{1}, c_{2}$ integrable on $[a, b]$ and two constants $C_{1}$ and $C_{2}$ with

$$
\int_{a}^{b} c_{1}(s) \mathrm{d} s \leqslant C_{1}, \quad \int_{a}^{b} c_{2}(s) \mathrm{d} s \leqslant C_{2}
$$

where $0<C_{2}<\frac{1}{2}\left(1-\mathrm{e}^{-\sigma}\right) / \alpha$ and $\|f(t, \varphi)\| \leqslant c_{1}(t)+c_{2}(t)\|\varphi(0)\|$ for each $t \in[a, b]$ and $\varphi \in C_{E}([-d, 0])$.
$\left(\mathrm{H}_{2}\right) \widehat{\mathcal{L}}:[a, b] \rightarrow L(E)$ is a strongly measurable and Bochner integrable operator on $[a, b]$.
$\left(\mathrm{H}_{3}\right)$ For each $\varepsilon>0$ there exists a closed subset $I_{\varepsilon}$ of $[a, b]$ with $\lambda\left([a, b]-I_{\varepsilon}\right)<\varepsilon$ such that for any nonempty bounded subset $A$ of $C_{E}([-d, 0])$ and for each closed subset $J \subseteq I_{\varepsilon}$, one has

$$
\gamma(F(J \times A)) \leqslant \sup _{t \in J} h(t, \beta(A(0))) .
$$

$\left(\mathrm{H}_{4}\right)$ Let

$$
\begin{aligned}
L & =\sup \left\{\int_{a}^{b}|K(t, s)| h(t, \gamma(B(s)) \mathrm{d} s: t \in[a, b]\}\right. \\
& \leqslant \sup \{\gamma(B(s)): s \in[a, b]\},
\end{aligned}
$$

where $B$ is a bounded subset of $C([a, b], E)$.
Then, for each $\psi \in C_{E}([a-d, a])$ such that $\psi(a)=0$, problem (Q) has at least one bounded solution on the interval $[a-d, b]$.

Proof. We partition the closed interval $[a, b]$ by the points: $t_{i}^{n}=(i b+(n-i) a) / n$ where $i=0,1,2, \ldots, n$ and $u_{n}$ will be defined by mathematical induction. Along the same lines as in [17], [16] we use some methods for functional equations. For each $(t, x) \in\left[a-d, t_{1}^{n}\right] \times E$ put

$$
\Phi_{1}^{n}(t, x)= \begin{cases}\psi(t) & \text { if } t \in[a-d, a] \\ n(t-a) x & \text { if } t \in\left[a, t_{1}^{n}\right]\end{cases}
$$

where $n$ is a positive integer. Let $f_{1}^{n}:\left[a, t_{1}^{n}\right] \times E \rightarrow E$ be a function defined by $f_{1}^{n}(t, x)=f^{d}\left(t, \tau_{t_{1}^{n}}\left(\Phi_{1}^{n}(\cdot, x)\right)\right)$. By Theorem 3.2 there is a bounded function $u_{n}$ : $\left[a-d, t_{1}^{n}\right] \rightarrow E$ with $u_{n}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{1}^{n}\right]$

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{1}^{n}\left(s, u_{n}(s)\right) \mathrm{d} s
$$

Now we can assume that the function $u_{n}$ such that $u_{n}=\psi$ on $[a-d, a]$ and

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{k}^{n}\left(s, u_{n}(s)\right) \mathrm{d} s, \quad t \in\left[a, t_{k}^{n}\right]
$$

with $f_{k}^{n}(t, x)=f^{d}\left(t, \tau_{t_{k}^{n}} \Phi_{n}^{k}(\cdot, x)\right)$ where $\Phi_{k}^{n}:\left[a-d, t_{k}^{n}\right] \times E \rightarrow E$ is defined by

$$
\Phi_{k}^{n}(t, x)= \begin{cases}u_{n}(t) & \text { if } t \in\left[a-d, t_{k-1}^{n}\right] \\ u_{k}^{n}\left(t_{k-1}^{n}\right)+n\left(t-t_{k-1}^{n}\right)\left(x-u_{k}^{n}\left(t_{k-1}^{n}\right)\right) & \text { if } t \in\left[t_{k-1}^{n}, t_{k}^{n}\right]\end{cases}
$$

We define $\Phi_{k+1}^{n}:\left[a-d, t_{k+1}^{n}\right] \times E \rightarrow E$ by

$$
\Phi_{k+1}^{n}(t, x)= \begin{cases}u_{n}(t) & \text { if } t \in\left[a-d, t_{k}^{n}\right] \\ u_{n}\left(t_{k}^{n}\right)+n\left(t-t_{k}^{n}\right)\left(x-u_{n}\left(t_{k}^{n}\right)\right) & \text { if } t \in\left[t_{k}^{n}, t_{k+1}^{n}\right]\end{cases}
$$

Now if $f_{k+1}^{n}:\left[a, t_{k+1}^{n}\right] \times E \rightarrow E$ is defined by $f_{k+1}^{n}(t, x)=f^{d}\left(t, \tau_{t_{k+1}^{n}}\left(\Phi_{k+1}^{n}(\cdot, x)\right)\right)$, then $f_{k+1}^{n}$ satisfies the conditions of Theorem 3.1. Hence there is a bounded function $u_{n}^{k+1}:\left[a, t_{k+1}^{n}\right] \rightarrow E$ such that for each $t \in\left[a, t_{k+1}^{n}\right]$

$$
u_{n}^{k+1}(t)=\int_{a}^{t} K(t, s) f_{k+1}^{n}\left(s, u_{n}^{k+1}(s)\right) \mathrm{d} s
$$

Put $u_{n}=u_{n}^{k+1}$ on $\left[t_{k}^{n}, t_{k+1}^{n}\right]$. Then we can consider $u_{n}$ is defined on $\left[a-d, t_{k+1}^{n}\right]$ with $u_{n}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{k+1}^{n}\right], u_{n}$ is defined by

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{k+1}^{n}\left(s, u_{n}(s)\right) \mathrm{d} s
$$

Consequently, for all $n \in \mathbb{N}$ we have a continuous bounded function $u_{n}$ such that $u_{n}=\psi$ on $[a-d, a]$ and for each $t \in[a, b], u_{n}$ is defined by

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f^{d}\left(s, \tau_{t_{k}^{n}} \Phi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right) \mathrm{d} s
$$

where $k \in\{1,2,3, \ldots, n\}$ is such that $t_{k-1}^{n} \leqslant t \leqslant t_{k}^{n}$. Set $W=\left\{u_{n}: n \in \mathbb{N}\right\}$. Now if $t_{1}, t_{2} \in[a, b]$ and $t_{1}<t_{2}$, then

$$
\begin{aligned}
\left\|u_{n}\left(t_{1}\right)-u_{n}\left(t_{2}\right)\right\| \leqslant & \int_{a}^{t_{1}}\left|K\left(t_{1}, s\right)-K\left(t_{2}, s\right)\right|\left\|f^{d}\left(s, \tau_{t_{k}^{n}} \Phi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)\right\| \mathrm{d} s \\
& +\int_{t_{1}}^{t_{2}}\left|K\left(t_{2}, s\right)\right|\left\|f^{d}\left(s, \tau_{t_{k}^{n}} \Phi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)\right\| \mathrm{d} s \\
\leqslant & \int_{a}^{t_{1}}\left|K\left(t_{1}, s\right)-K\left(t_{2}, s\right)\right|\left(c_{1}(s)+c_{2}(s)\left\|u_{n}(s)\right\|\right) \mathrm{d} s \\
& +\alpha \int_{t_{1}}^{t_{2}} \mathrm{e}^{-\sigma\left|t_{2}-s\right|}\left(c_{1}(s)+c_{2}(s)\left\|u_{n}(s)\right\|\right) \mathrm{d} s
\end{aligned}
$$

Since $u_{n}$ is bounded, $|K(t, s)| \leqslant \alpha \mathrm{e}^{-\sigma|t-s|}$ and $u_{n}=\psi$ on $[a-d, a]$ hence $W$ is equicontinuous in $C_{E}[a-d, b]$. Moreover, we can define a mapping $\psi^{\prime}$ by

$$
\psi^{\prime}(x)(t)=\int_{a}^{t} K(t, s) f(s, x(s)) \mathrm{d} s \quad \text { for each } t \in[a, b],
$$

so $\psi^{\prime}(H(t))=\psi^{\prime}\left(\left\{u_{n}(t): n \in \mathbb{N}\right\}\right)$ and $\psi(H(a))=0$. We can show that $\psi^{\prime}(H(t))=0$ for all $t \in[a, b]$.

Consider $a \leqslant t<x \leqslant b$. Along the same lines as in the proof Theorem 3.1 if we replace the interval $[t-q, t+q]$ by $[t, x]$ and the set $D$ by $W$, then we have

$$
\gamma\left(\psi^{\prime}(H(t))\right) \leqslant \int_{P}|K(t, s)| h(s, \gamma(H(s))) \mathrm{d} s \leqslant \int_{t}^{x}|K(t, s)| h(s, \gamma(H(s))) \mathrm{d} s
$$

and

$$
\gamma\left(\psi^{\prime}(H(x)) \leqslant \gamma\left(\psi^{\prime}(W)(t)\right)+\gamma\left(\int_{t}^{x} K(t, s) f(s, H(s)) \mathrm{d} s\right) .\right.
$$

Define $\varrho(t):=\gamma(H(t))$; since $\gamma(H(t))=\gamma\left(\psi^{\prime}(H(t))\right)$, so $\varrho(a)=0$ and we get

$$
\varrho(x)-\varrho(t) \leqslant \gamma\left(\int_{t}^{x} K(t, s) f(s, H(s)) \mathrm{d} s\right) \leqslant \int_{t}^{x}|K(t, s)| h(s, \varrho(s)) \mathrm{d} s .
$$

Therefore $\dot{\varrho}(t) \leqslant \alpha \mathrm{e}^{-\sigma|t-s|} h(t, \varrho(t))$ a.e., thus $\varrho \equiv 0$.

By Ascoli's theorem the sequence $\left(u_{n}\right)_{n \in \mathbb{N}}$ converges weakly uniformly to a function $u \in C_{E}([a-d, b])$ with $u=\psi$ on $[a-d, a]$.

For simplicity we will denote the function $f^{d}\left(s, \tau_{t_{k}^{n}} \Phi_{k}^{n}\left(\cdot, u_{n}(s)\right)\right)$ by $h_{n}^{k}(s)$ and we have $\Phi\left(\left\{h_{n}^{k}(t): n \in \mathbb{N}\right\}\right)=0$, so $\left\{h_{n}^{k}(t): n \in \mathbb{N}\right\}$ is relatively weakly compact.

Now if we create a multivalued function

$$
F(t)=\overline{\operatorname{conv}}\left\{h_{n}^{k}(t): n \in \mathbb{N}\right\},
$$

then $F(t)$ is nonempty convex and weakly compact. The set

$$
\delta_{F}^{1}:=\left\{l \in L^{1}(I, E): l(t) \in F(t)\right\}
$$

is nonempty convex and weakly compact, thus by the Eberlein-Śmulian theorem there exists a subsequence $\left(h_{n_{j}}^{k}\right)$ of $\left(h_{n}^{k}\right)$ such that $h_{n_{j}}^{k} \rightarrow l$ weakly, $l \in \delta_{F}^{1}$. Thus $u_{n}$ tends weakly to $\int_{a}^{t} K(t, s) l(s) \mathrm{d} s$. Moreover, for each $n \in \mathbb{N}, u_{n} \in C_{E}([a-d, b])$, $u_{n}$ converges uniformly to $u$ on each compact subset of $[a-d, b]$ and $u$ is uniformly continuous on $[a-d, a]$. But for each $t \in[a, b]$ we can find $n \in \mathbb{N}$ such that $d>$ $(b-a) / n$ and $t \in\left[t_{k-1}^{n}, t_{k}^{n}\right]$ for some $k$ in the set $\{1,2, \ldots, n\}$. Now

$$
\begin{aligned}
& \left\|\tau_{t_{k}^{n}} \Phi_{k}^{n}\left(\cdot, u_{n}(t)\right)-\tau_{t} u\right\| \leqslant \sup _{s \in[-d,(a-b) / n]}\left[\left\|\Phi_{k}^{n}\left(t_{k}^{n}+s, u_{n}(t)\right)-u\left(t_{k}^{n}+s\right)\right\|\right. \\
& \left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
& +\sup _{s \in[(a-b) / n, 0]}\left[\left(\| u_{n}\left(t_{k-1}^{n}\right)+n\left(t_{k}^{n}+s-t_{k-1}^{n}\right)\right.\right. \\
& \left.\times\left(u_{n}(t)-u_{n}\left(t_{k-1}^{n}\right)\right)-u\left(t_{k}^{n}+s\right) \|\right) \\
& \left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
& \leqslant \sup _{s \in[-d,(a-b) / n]}\left[\left\|u_{n}\left(t_{k}^{n}+s\right)-u\left(t_{k}^{n}+s\right)\right\|\right. \\
& \left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right] \\
& +\sup _{s \in[(a-b) / n, 0]}\left[\left((b-a)\left\|u_{n}(t)-u_{n}\left(t_{k-1}^{n}\right)\right\|\right.\right. \\
& +\left\|u_{n}\left(t_{k-1}^{n}\right)-u\left(t_{k}^{n}+s\right)\right\| \\
& \left.\left.+\left\|u\left(t_{k}^{n}+s\right)-u(t+s)\right\|\right)\right] \rightarrow 0 \quad \text { as } n \rightarrow \infty .
\end{aligned}
$$

Thus by Lemma 2.7 we conclude that $u(\cdot)$ is the desired solution of (Q).

Theorem 4.3. We assume:
$\left(\mathrm{H}_{1}^{\prime}\right) f^{\prime d}:[a, b] \times C([-d, 0], E) \rightarrow E$ is a function such that
(i) $t \mapsto f^{\prime d}(t, \varphi)$ is measurable,
(ii) $\varphi \mapsto f^{\prime d}(t, \varphi)$ is continuous,
(iii) for all $\varphi \in C([-d, 0], E)$, $f^{\prime d}([a, b] \times\{\varphi\})$ is separable.
$\left(\mathrm{H}_{2}\right) \widehat{\mathcal{L}}:[a, b] \rightarrow L(E)$ is a strongly measurable and Bochner integrable operator on $[a, b]$ and the linear equation

$$
\dot{x}(t)=\widehat{\mathcal{L}}(t) x(t)
$$

has a trichotomy with constants $\alpha \geqslant 1$ and $\sigma>0$.
$\left(\mathrm{H}_{3}\right)$ There exist two real nonnegative functions $c_{1}, c_{2}$ integrable on $[a, b]$ and two constants $C_{1}$ and $C_{2}$ with

$$
\int_{a}^{b} c_{1}(s) \mathrm{d} s \leqslant C_{1}, \quad \int_{a}^{b} c_{2}(s) \mathrm{d} s \leqslant C_{2}
$$

where $0<C_{2}<\left(1-\mathrm{e}^{-\sigma}\right) /(2 \alpha)$ and $\left\|f^{\prime d}(t, \varphi)\right\| \leqslant c_{1}(t)+c_{2}(t)\|\varphi(0)\|$ for each $t \in[a, b]$ and $\varphi \in C([-d, 0], E)$.
$\left(\mathrm{H}_{4}\right)$ For each $\varepsilon>0$ there exists a closed subset $I_{\varepsilon}$ of $[a, b]$ with $\lambda\left([a, b]-I_{\varepsilon}\right)<\varepsilon$ such that for any nonempty bounded subset $A$ of $C([-d, 0], E)$ and for each closed subset $J \subseteq I_{\varepsilon}$, one has

$$
\gamma\left(f^{\prime d}(J \times A)\right) \leqslant \sup _{t \in J} h(t, \gamma(A(0))) .
$$

Then, for each $\psi \in C([a-d, a], E)$ such that $\psi(a)=0$, problem (Q) has a weak solution on the interval $[a-d, b]$.

Proof. We partition the closed interval $[a, b]$ by the points: $t_{i}^{n}=(i b+(n-i) a) / n$ where $i=0,1,2, \ldots, n$. For each $n \in \mathbb{N}$, let $\xi_{1}^{n}:\left[a-d, t_{1}^{n}\right] \times E \rightarrow E$ be a function defined by

$$
\xi_{1}^{n}(t, x)= \begin{cases}\psi(t) & \text { if } t \in[a-d, a], \\ n(t-a) x & \text { if } t \in\left[a, t_{1}^{n}\right] .\end{cases}
$$

Assume that $f_{1}^{\prime n}:\left[a, t_{1}^{n}\right] \times E \rightarrow E$ is defined by $f_{1}^{\prime n}(t, x)=f^{\prime d}\left(t, \tau_{t_{1}^{n}}\left(\xi_{1}^{n}(\cdot, x)\right)\right)$. By Theorem 3.3 there is a function $v_{n}^{\prime}:\left[a-d, t_{1}^{n}\right] \rightarrow E$ such that $v_{n}^{\prime}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{1}^{n}\right]$

$$
v_{n}^{\prime}(t)=\int_{a}^{t} K(t, s) f_{1}^{\prime n}\left(s, v_{n}^{\prime}(s)\right) \mathrm{d} s
$$

As in Theorem 4.1 there exists a function $u_{n}:\left[-d, t_{k}^{n}\right] \rightarrow E$ defined by $u_{n}=\psi$ on [ $a-d, a]$ and

$$
u_{n}(t)=\int_{a}^{t} K(t, s) f_{k}^{\prime n}\left(s, u_{n}(s)\right) \mathrm{d} s, \quad t \in\left[a, t_{k}^{n}\right]
$$

where $f_{k}^{\prime n}(t, x)=f^{\prime d}\left(t, \tau_{t_{k}^{n}} \xi_{n}^{k}(\cdot, x)\right)$ and $\xi_{k}^{n}:\left[a-d, t_{k}^{n}\right] \times E \rightarrow E$ is defined by

$$
\xi_{k}^{n}(t, x)= \begin{cases}u_{n}(t) & \text { if } t \in\left[a-d, t_{k-1}^{n}\right], \\ u_{n}\left(t_{k-1}^{n}\right)+n\left(t-t_{k-1}^{n}\right)\left(x-u_{n}\left(t_{k-1}^{n}\right)\right) & \text { if } t \in\left[t_{k-1}^{n}, t_{k}^{n}\right] .\end{cases}
$$

At this point we can complete the proof as that of Theorem 4.1.
In the next theorem we let $\mathfrak{h}:[a, b] \times \mathbb{R}^{a} \rightarrow \mathbb{R}^{+}$be a Carathéodory function and, for each bounded subset $Z$ of $[a, b] \times \mathbb{R}^{a}$, let there exist a measurable function $m_{Z}$ such that $\mathfrak{h}(t, s) \leqslant m_{Z}(t)$ for each $(t, s) \in Z$ and $m$ is integrable on $[c, T]$ for each $c$; $a<c \leqslant b$. Moreover, let for each $c ; a<c \leqslant b$, the identically zero function be the only absolutely continuous function on $[a, c]$ which satisfies $\dot{u}(t)=\mathfrak{h}(t, u(t))$ a.e. on $[a, c]$ such that the right hand derivative of $u(t)$ at $t=a, D_{+} u(a)$, exists and $D_{+} u(a)=u(a)=0$.

We note that the assumptions on $\mathfrak{h}$ are weaker than those on a Kamke function $w$.

Theorem 4.4. In the setting of Theorem 4.3 we replace a Kamke function $w$ by a function $\mathfrak{h}$ and suppose that $f^{\prime d}$ is bounded and continuous instead of (i) and (ii) in condition $\left(\mathrm{H}_{1}^{\prime}\right)$. Then, for each $\psi \in C([a-d, a], E)$ such that $\psi(a)=0$, problem (Q) has a weak solution on the interval $[a-d, b]$.

We omit the proof since it runs as the proof of Theorem 4.3 except that we replace the use of Theorem 3.3 by that of Theorem 3.4 to find a continuous function $v_{n}$ such that $v_{n}=\psi$ on $[a-d, a]$ and for each $t \in\left[a, t_{1}^{n}\right]$

$$
v_{n}(t)=\int_{a}^{t} K(t, s) f_{1}^{n}\left(s, v_{n}(s)\right) \mathrm{d} s
$$

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